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Nonlinear Output Regulation - Jie Huang 2004-11-01
This book provides a comprehensive and in-depth treatment of the nonlinear output regulation problem.

Design of Linear Multivariable Feedback Control Systems - Joseph J. Bongiorno Jr. 2020-07-09
This book contains a derivation of the subset of stabilizing controllers for analog and digital linear time-invariant multivariable feedback control systems that insure stable system errors and stable controller outputs for persistent deterministic reference inputs that are trackable and for persistent deterministic disturbance inputs that are rejectable. For this subset of stabilizing controllers, the Wiener-Hopf methodology is then employed to obtain the optimal controller for which a quadratic performance measure is minimized. This is done for the completely general standard configuration and methods that enable the trading off of optimality for an improved stability margin and/or reduced sensitivity to plant model uncertainty are described. New and novel results on the optimal design of decoupled (non-interacting) systems are also presented. The results are applied in two examples: the one- and three-degree-of-freedom configurations. These demonstrate that the standard configuration is one encompassing all possible feedback configurations. Each chapter is completed by a group of worked examples, which reveal additional insights and extensions of the theory presented in the chapter. Three of the examples illustrate the application of the theory to two physical cases: the depth and pitch control of a submarine and the control of a Rosenbrock process. In the latter case, designs with and without decoupling are compared. This book provides researchers and graduate students working in feedback control with a valuable reference for Wiener–Hopf theory of multivariable design. Basic knowledge of linear systems and matrix theory is required.

A Course in Robust Control Theory - Geir E. Dullerud 2013-03-14
During the 90s robust control theory has seen major advances and achieved a new maturity, centered around the notion of convexity. The goal of this book is to give a graduate-level course on this theory that emphasizes these new developments, but at the same time conveys the main principles and ubiquitous tools at the heart of the subject. Its pedagogical objectives are to introduce a coherent and unified framework for studying the theory, to provide students with the control-theoretic background required to read and contribute to the research literature, and to present the main ideas and demonstrations of the major results. The book will be of value to mathematical researchers and computer scientists, graduate students planning to do research in the area, and engineering practitioners requiring advanced control techniques.

Mathematics for Machine Learning - Marc Peter Deisenroth 2020-04-23
The fundamental mathematical tools needed to understand machine learning include linear algebra, analytic geometry, matrix decompositions, vector calculus, optimization, probability and statistics. These topics are traditionally taught in disparate courses, making it hard for data science or computer science students, or professionals, to efficiently learn the mathematics. This self-contained textbook bridges the gap between mathematical and machine learning texts, introducing the mathematical concepts with a minimum of prerequisites. It uses these concepts to derive four central machine learning methods: linear regression, principal component analysis, Gaussian mixture models and support vector machines. For students and others with a mathematical background, these derivations provide a starting point to machine learning texts. For those learning the mathematics for the first time, the methods help build intuition and practical experience with applying mathematical concepts. Every chapter includes worked examples and exercises to test understanding. Programming tutorials are offered on the book's web site.

Mathematical Computation with Maple V: Ideas and Applications - Thomas Lee 2012-12-06
Developments in both computer hardware and Perhaps the greatest impact has been felt by the software over the decades have fundamentally education community. Today, it is nearly changed the way people solve problems. impossible to find a college or university that has Technical professionals have greatly benefited not introduced mathematical computation in from new tools and techniques that have allowed some form, into the curriculum. Students now them to be more efficient, accurate, and creative have regular access to the amount of in their work. computational power that were available to a very exclusive set of researchers five years ago. This Maple V and the new generation of mathematical has produced tremendous pedagogical computation systems have the potential of challenges and opportunities. having the same kind of revolutionary impact as high-level general purpose programming Comparisons to the calculator revolution of the languages (e.g. FORTRAN, BASIC, C), 70's are inescapable. Calculators have application software (e.g. spreadsheets, extended the average person's ability to solve Computer Aided Design - CAD), and even common problems more efficiently, and calculators have had. Maple V has amplified our arguably, in better ways. Today, one needs at mathematical abilities: we can solve more least a calculator to deal with standard problems problems more accurately, and more often. In in life -budgets, mortgages, gas mileage, etc. specific disciplines, this amplification has taken For business people or professionals, the excitingly different forms.

Direct Methods for Sparse Linear Systems - Timothy A. Davis 2006-09-01
The sparse backslash book. Everything you wanted to know but never dared to ask about modern direct linear solvers. Chen Greif, Assistant Professor, Department of Computer Science, University of British Columbia.Overall, the book is magnificent. It fills a long-felt need for an accessible textbook on modern sparse direct methods. Its choice of scope is excellent John Gilbert, Professor, Department of Computer Science, University of California, Santa Barbara.Computational scientists often encounter problems requiring the solution of sparse systems of linear equations. Attacking these problems efficiently requires an in-depth knowledge of the underlying theory, algorithms, and data structures found in sparse matrix software libraries. Here, Davis presents the fundamentals of sparse matrix algorithms to provide the requisite background. The book includes CSparse, a concise downloadable sparse matrix package that illustrates the algorithms and theorems presented in the book and equips readers with the tools necessary to understand larger and more complex software packages.With a strong emphasis on MATLAB and the C programming language, Direct Methods for Sparse Linear Systems equips readers with the working knowledge required to use sparse solver packages and write code to interface applications to those packages. The book also explains how MATLAB performs its sparse matrix computations.Audience This invaluable book is essential to computational scientists and software developers who want to understand the theory and algorithms behind modern techniques used to solve large sparse linear systems. The book also serves as an excellent practical resource for students with an interest in combinatorial scientific computing.Preface; Chapter 1: Introduction; Chapter 2: Basic algorithms; Chapter 3: Solving triangular systems; Chapter 4: Cholesky factorization; Chapter 5: Orthogonal methods; Chapter 6: LU factorization; Chapter 7: Fill-reducing orderings; Chapter 8: Solving sparse linear systems; Chapter 9: CSparse; Chapter 10: Sparse matrices in MATLAB; Appendix: Basics of the C programming language; Bibliography; Index.

Control Theory for Linear Systems - Harry L. Trentelman 2012-12-06 Control Theory for Linear Systems deals with the mathematical theory of feedback control of linear systems. It treats a wide range of control synthesis problems for linear state space systems with inputs and outputs. The book provides a treatment of these problems using state space methods, often with a geometric flavour. Its subject matter ranges from controllability and observability, stabilization, disturbance decoupling, and tracking and regulation, to linear quadratic regulation, H2 and H-infinity control, and robust stabilization. Each chapter of the book contains a series of exercises, intended to increase the reader's understanding of the material. Often, these exercises generalize and extend the material treated in the regular text.

A First Course in Numerical Methods - Uri M. Ascher 2011-07-14 Offers students a practical knowledge of modern techniques in scientific computing.

Multidisciplinary Research in Control - Laura Giarré 2003-09-04 The Mohammed Dahleh symposium brought together leading researchers in several areas of engineering and science. Many of the presentations focused on new emerging research areas of key significance. These new areas have in common that the dynamics and control theory and methods provide the appropriate framework for the understanding of the corresponding phenomena, while at the same time providing many of the tools necessary for their application to relevant technologies. Examples of these opportunities include the areas of systems biology, quantum feedback and control, fluid dynamics, and control applications in nanotechnology. This collected volume demonstrates the importance of these emerging areas in the current research agenda in science and technology and shows that a unique opportunity exists to drastically extend the scope and impact of dynamics and control methods far beyond their traditional areas of application in engineering.

Computer-Controlled Systems - Karl J Åström 2013-06-13 This volume features computational tools that can be applied directly and are explained with simple calculations, plus an emphasis on control system principles and ideas. Includes worked examples, MATLAB macros, and solutions manual.

Plasticity for Structural Engineers - Wai-Fah Chen 2007-02-15 J. Ross Publishing Classics are world-renowned texts and monographs written by preeminent scholars. These books are suitable for students, researchers, professionals and libraries.

Sound Systems: Design and Optimization - Bob McCarthy 2016-02-26 Sound Systems: Design and Optimization provides an accessible and unique perspective on the behavior of sound systems in the practical world. The third edition reflects current trends in the audio field thereby providing readers with the newest methodologies and techniques. In this greatly expanded new edition, you'll find clearer explanations, a more streamlined organization, increased coverage of current technologies and comprehensive case studies of the author's award-winning work in the field. As the only book devoted exclusively to modern tools and techniques in this emerging field, Sound Systems: Design and Optimization provides the specialized guidance needed to perfect your design skills. This book helps you: Improve your design and optimization decisions by understanding how audiences perceive reinforced sound Use modern analyzers and prediction programs to select speaker placement, equalization, delay and level settings based on how loudspeakers interact in the space Define speaker array configurations and design strategies that maximize the potential for spatial uniformity Gain a comprehensive understanding of the tools and techniques required to generate a design that will create a successful transmission/reception model

A Linear Systems Primer - Panos J. Antsaklis 2007-12-03 Based on a streamlined presentation of the authors' successful work Linear Systems, this textbook provides an introduction to systems theory with an emphasis on control. Initial chapters present necessary mathematical background material for a fundamental understanding of the dynamical behavior of systems. Each chapter includes helpful chapter descriptions and guidelines for the reader, as well as summaries, notes, references, and exercises at the end. The emphasis throughout is on time-invariant systems, both continuous- and discrete-time.

Decoupling Control - Qing-Guo Wang 2003-07-01 Decoupling or non-interactive control has attracted considerable research attention since the 1960s when control engineers started to deal with multivariable systems. The theory and design techniques for decoupling control have now, more or less matured for linear time-invariant systems, yet there is no single book which focuses on such an

important topic. The present monograph fills this gap by presenting a fairly comprehensive and detailed treatment of decoupling theory and relevant design methods. Decoupling control under the framework of polynomial transfer function and frequency response settings, is included as well as the disturbance decoupling problem. The emphasis here is on special or relatively new compensation schemes such as (true and virtual) feedforward control and disturbance observers, rather than use of feedback control alone. The results are presented in a self-contained way and only the knowledge of basic linear systems theory is assumed of the reader.

Linear Systems - Panos J. Antsaklis 2006-11-24 "There are three words that characterize this work: thoroughness, completeness and clarity. The authors are congratulated for taking the time to write an excellent linear systems textbook!" —IEEE Transactions on Automatic Control Linear systems theory plays a broad and fundamental role in electrical, mechanical, chemical and aerospace engineering, communications, and signal processing. A thorough introduction to systems theory with emphasis on control is presented in this self-contained textbook, written for a challenging one-semester graduate course. A solutions manual is available to instructors upon adoption of the text. The book's flexible coverage and self-contained presentation also make it an excellent reference guide or self-study manual. For a treatment of linear systems that focuses primarily on the time-invariant case using streamlined presentation of the material with less formal and more intuitive proofs, please see the authors' companion book entitled A Linear Systems Primer.

Templates for the Solution of Linear Systems - Richard Barrett 1994-01-01 In this book, which focuses on the use of iterative methods for solving large sparse systems of linear equations, templates are introduced to meet the needs of both the traditional user and the high-performance specialist. Templates, a description of a general algorithm rather than the executable object or source code more commonly found in a conventional software library, offer whatever degree of customization the user may desire. Templates offer three distinct advantages: they are general and reusable; they are not language specific; and they exploit the expertise of both the numerical analyst, who creates a template reflecting in-depth knowledge of a specific numerical technique, and the computational scientist, who then provides "value-added" capability to the general template description, customizing it for specific needs. For each template that is presented, the authors provide: a mathematical description of the flow of algorithm; discussion of convergence and stopping criteria to use in the iteration; suggestions for applying a method to special matrix types; advice for tuning the template; tips on parallel implementations; and hints as to when and why a method is useful.

Control Theory and Systems Biology - Pablo A. Iglesias 2010 A survey of how engineering techniques from control and systems theory can be used tohelp biologists understand the behavior of cellular systems.

Generalized Sylvester Equations - Guang-Ren Duan 2015-06-09 Provides One Unified Formula That Gives Solutions to Several Types of GSEs Generalized Sylvester equations (GSEs) are applied in many fields, including applied mathematics, systems and control, and signal processing. Generalized Sylvester Equations: Unified Parametric Solutions presents a unified parametric approach for solving various types of GSEs. In an extremely neat and elegant matrix form, the book provides a single unified parametric solution formula for all the types of GSEs, which further reduces to a specific clear vector form when the parameter matrix F in the equations is a Jordan matrix. Particularly, when the parameter matrix F is diagonal, the reduced vector form becomes extremely simple. The first chapter introduces several types of GSEs and gives a brief overview of solutions to GSEs. The two subsequent chapters then show the importance of GSEs using four typical control design applications and discuss the F-coprimeness of a pair of polynomial matrices. The next several chapters deal with parametric solutions to GSEs. The final two chapters present analytical solutions to normal Sylvester equations (NSEs), including the well-known continuous- and discrete-time Lyapunov equations. An appendix provides the proofs of some theorems. The book can be used as a reference for graduate and senior undergraduate courses in applied mathematics and control systems analysis and design. It will also be useful to readers interested in research and applications based on Sylvester equations.

Microprocessor-Based Control Systems - N.K. Sinha 2012-12-06 Recent advances in LSI technology and the consequent availability of

inexpensive but powerful microprocessors have already affected the process control industry in a significant manner. Microprocessors are being increasingly utilized for improving the performance of control systems and making them more sophisticated as well as reliable. Many concepts of adaptive and learning control theory which were considered impractical only 20 years ago are now being implemented. With these developments there has been a steady growth in hardware and software tools to support the microprocessor in its complex tasks. With the current trend of using several microprocessors for performing the complex tasks in a modern control system, a great deal of emphasis is being given to the topic of the transfer and sharing of information between them. Thus the subject of local area networking in the industrial environment has become assumed great importance. The object of this book is to present both hardware and software concepts that are important in the development of microprocessor-based control systems. An attempt has been made to obtain a balance between theory and practice, with emphasis on practical applications. It should be useful for both practicing engineers and students who are interested in learning the practical details of the implementation of microprocessor-based control systems. As some of the related material has been published in the earlier volumes of this series, duplication has been avoided as far as possible.

Lyapunov Matrix Equation in System Stability and Control - Zoran Gajic 2008-01-01
This comprehensive treatment provides solutions to many engineering and mathematical problems related to the Lyapunov matrix equation, with self-contained chapters for easy reference. The authors offer a wide variety of techniques for solving and analyzing the algebraic, differential, and difference Lyapunov matrix equations of continuous-time and discrete-time systems. 1995 edition.

Linear State-Space Control Systems - Robert L. Williams, II 2007-02-09
The book blends readability and accessibility common to undergraduate control systems texts with the mathematical rigor necessary to form a solid theoretical foundation. Appendices cover linear algebra and provide a Matlab overivew and files. The reviewers pointed out that this is an ambitious project but one that will pay off because of the lack of good up-to-date textbooks in the area.

Linear Systems Theory - Ben M. Chen 2004-08-27
Includes MATLAB-based computational and design algorithms utilizing the "Linear Systems Toolkit." All results and case studies presented in both the continuous- and discrete-time settings.

Linear Systems Theory - Ben M. Chen 2012-12-06
Includes MATLAB-based computational and design algorithms utilizing the "Linear Systems Toolkit." All results and case studies presented in both the continuous- and discrete-time settings.

Analog and Digital Control System Design - Chi-Tsong Chen 2006-02-24
This text's contemporary approach focuses on the concepts of linear control systems, rather than computational mechanics. Straightforward coverage includes an integrated treatment of both classical and modern control system methods. The text emphasizes design with discussions of problem formulation, design criteria, physical constraints, several design methods, and implementation of compensators. Discussions of topics not found in other texts—such as pole placement, model matching and robust tracking—add to the text's cutting-edge presentation. Students will appreciate the applications and discussions of practical aspects, including the leading problem in developing block diagrams, noise, disturbances, and plant perturbations. State feedback and state estimators are designed using state variable equations and transfer functions, offering a comparison of the two approaches. The incorporation of MATLAB throughout the text helps students to avoid time-consuming computation and concentrate on control system design and analysis.

Fundamentals of Linear State Space Systems - John S. Bay 1999
This book addresses two primary deficiencies in the linear systems textbook market: a lack of development of state space methods from the basic principles and a lack of pedagogical focus. The book uses the geometric intuition provided by vector space analysis to develop in a very sequential manner all the essential topics in linear state system theory that a senior or beginning graduate student should know. It does this in an ordered, readable manner, with examples drawn from several areas of engineering. Because it derives state space methods from linear algebra and vector spaces and ties all the topics together with diverse applications, this book is suitable for students from any engineering

discipline, not just those with control systems backgrounds and interests. It begins with the mathematical preliminaries of vectors and spaces, then emphasizes the geometric properties of linear operators. It is from this foundation that the studies of stability, controllability and observability, realizations, state feedback, observers, and Kalman filters are derived. There is a direct and simple path from one topic to the next. The book includes both discrete- and continuous-time systems, introducing them in parallel and emphasizing each in appropriate context. Time-varying systems are discussed from generality and completeness, but the emphasis is on time-invariant systems, and only in time-domain; there is no treatment of matrix fraction descriptions or polynomial matrices. Tips for using MATLAB are included in the form of margin notes, which are placed wherever topics with applicable MATLAB commands are introduced. These notes direct the reader to an appendix, where a MATLAB command reference explains command usage. However, an instructor or student who is not interested in MATLAB usage can easily skip these references without interrupting the flow of text.

Polynomial Methods for Control Systems Design - Michael J. Grimble 2012-12-06
This monograph was motivated by a very successful workshop held before the 3rd IEEE Conference on Decision and Control held at the Buena Vista Hotel, lake Buena Vista, Florida, USA. The workshop was held to provide an overview of polynomial system methods in LQG (or H) and Hoo optimal control and 2 estimation. The speakers at the workshop were chosen to reflect the important contributions polynomial techniques have made to systems theory and also to show the potential benefits which should arise in real applications. An introduction to H2 control theory for continuous-time systems is included in chapter 1. Three different approaches are considered covering state-space model descriptions, Wiener-Hopf transfer function methods and finally polyno mial equation based transfer function solutions. The differences and similarities between the techniques are explored and the different assumptions employed in the solutions are discussed. The standard control system description is intro duced in this chapter and the use of Hardy spaces for optimization. Both control and estimation problems are considered in the context of the standard system description. The tutorial chapter concludes with a number of fully worked ex amples.

Parallel Algorithms for Optimal Control of Large Scale Linear Systems - Zoran Gajic 2012-12-06
Parallel Algorithms for Optimal Control of Large Scale Linear Systems is a comprehensive presentation for both linear and bilinear systems. The parallel algorithms presented in this book are applicable to a wider class of practical systems than those served by traditional methods for large scale singularly perturbed and weakly coupled systems based on the power-series expansion methods. It is intended for scientists and advance graduate students in electrical engineering and computer science who deal with parallel algorithms and control systems, especially large scale systems. The material presented is both comprehensive and unique.

Modern Control Theory - William L. Brogan 1982

Controlled and Conditioned Invariants in Linear System Theory - Giuseppe Basile 1992
Using a geometric approach to system theory, this work discusses controlled and conditioned invariance to geometrical analysis and design of multivariable control systems, presenting new mathematical theories, new approaches to standard problems and applied mathematics topics.

Computer Aided Design in Control Systems 1988 - Zhen-Yu Chen 2014-06-28
This volume contains 73 papers, presenting the state of the art in computer-aided design in control systems (CADCS). The latest information and exchange of ideas presented at the Symposium illustrates the development of computer-aided design science and technology within control systems. The Proceedings contain six plenary papers and six special invited papers, and the remainder are divided into five themes: CADCS packages; CADCS software and hardware; systems design methods; CADCS expert systems; CADCS applications, with finally a discussion on CADCS in education and research.

Linear Systems Theory - João P. Hespanha 2018-02-13
A fully updated textbook on linear systems theory Linear systems theory is the cornerstone of control theory and a well-established discipline that focuses on linear differential equations from the perspective of control and estimation. This updated second edition of Linear Systems Theory covers the subject's key topics in a unique lecture-style format, making the book easy to use for instructors and students. João Hespanha looks at

system representation, stability, controllability and state feedback, observability and state estimation, and realization theory. He provides the background for advanced modern control design techniques and feedback linearization and examines advanced foundational topics, such as multivariable poles and zeros and LQG/LQR. The textbook presents only the most essential mathematical derivations and places comments, discussion, and terminology in sidebars so that readers can follow the core material easily and without distraction. Annotated proofs with sidebars explain the techniques of proof construction, including contradiction, contraposition, cycles of implications to prove equivalence, and the difference between necessity and sufficiency. Annotated theoretical developments also use sidebars to discuss relevant commands available in MATLAB, allowing students to understand these tools. This second edition contains a large number of new practice exercises with solutions. Based on typical problems, these exercises guide students to succinct and precise answers, helping to clarify issues and consolidate knowledge. The book's balanced chapters can each be covered in approximately two hours of lecture time, simplifying course planning and student review. Easy-to-use textbook in unique lecture-style format Sidebars explain topics in further detail Annotated proofs and discussions of MATLAB commands Balanced chapters can each be taught in two hours of course lecture New practice exercises with solutions included

The Mathematics of Shock Reflection-Diffraction and von Neumann's Conjectures - Gui-Qiang G Chen 2018-02-27
This book offers a survey of recent developments in the analysis of shock reflection-diffraction, a detailed presentation of original mathematical proofs of von Neumann's conjectures for potential flow, and a collection of related results and new techniques in the analysis of partial differential equations (PDEs), as well as a set of fundamental open problems for further development. Shock waves are fundamental in nature. They are governed by the Euler equations or their variants, generally in the form of nonlinear conservation laws—PDEs of divergence form. When a shock hits an obstacle, shock reflection-diffraction configurations take shape. To understand the fundamental issues involved, such as the structure and transition criteria of different configuration patterns, it is essential to establish the global existence, regularity, and structural stability of shock reflection-diffraction solutions. This involves dealing with several core difficulties in the analysis of nonlinear PDEs—mixed type, free boundaries, and corner singularities—that also arise in fundamental problems in diverse areas such as continuum mechanics, differential geometry, mathematical physics, and materials science. Presenting recently developed approaches and techniques, which will be useful for solving problems with similar difficulties, this book opens up new research opportunities.

Instructor's Solutions Manual for Chen's Signals and Systems - Chi-Tsong Chen 2004-03
'Instructor's Solutions Manual for Chen's Signals and Systems', third edition is a supplementary material that contains solutions to problems featured in the main text. It is available free of charge to adopting professors.

Digital Control Engineering - M. Sami Fadali 2012-08-21
Digital controllers are part of nearly all modern personal, industrial, and transportation systems. Every senior or graduate student of electrical, chemical or mechanical engineering should therefore be familiar with the basic theory of digital controllers. This new text covers the fundamental principles and applications of digital control engineering, with emphasis on engineering design. Fadali and Visioli cover analysis and design of digitally controlled systems and describe applications of digital controls in a wide range of fields. With worked examples and Matlab applications in every chapter and many end-of-chapter assignments, this text provides both theory and practice for those coming to digital control engineering for the first time, whether as a student or practicing engineer. Extensive Use of computational tools: Matlab sections at end of each chapter show how to implement concepts from the chapter Frees the student from the

drudgery of mundane calculations and allows him to consider more subtle aspects of control system analysis and design An engineering approach to digital controls: emphasis throughout the book is on design of control systems. Mathematics is used to help explain concepts, but throughout the text discussion is tied to design and implementation. For example coverage of analog controls in chapter 5 is not simply a review, but is used to show how analog control systems map to digital control systems Review of Background Material: contains review material to aid understanding of digital control analysis and design. Examples include discussion of discrete-time systems in time domain and frequency domain (reviewed from linear systems course) and root locus design in s-domain and z-domain (reviewed from feedback control course) Inclusion of Advanced Topics In addition to the basic topics required for a one semester senior/graduate class, the text includes some advanced material to make it suitable for an introductory graduate level class or for two quarters at the senior/graduate level. Examples of optional topics are state-space methods, which may receive brief coverage in a one semester course, and nonlinear discrete-time systems Minimal Mathematics Prerequisites The mathematics background required for understanding most of the book is based on what can be reasonably expected from the average electrical, chemical or mechanical engineering senior. This background includes three semesters of calculus, differential equations and basic linear algebra. Some texts on digital control require more

Linear System Theory and Design - Chi-Tsong Chen 2014-02-27
Striking a balance between theory and applications, Linear System Theory and Design, INternational Fourth Edition, uses simple and efficient methods to develop results and design procedures that students can readily employ. Ideal for advanced underrrgraduate courses and first-year graduate courses in linear systems and multivariable system design, it is also a helpful resource for practicing engineers.

Electric Power System Dynamics - Yao-nan Yu 1983

Nonlinear System Theory - Wilson J. Rugh 1981

Numerical Methods for Linear Control Systems - Biswa Datta 2004-02-24
Numerical Methods for Linear Control Systems Design and Analysis is an interdisciplinary textbook aimed at systematic descriptions and implementations of numerically-viable algorithms based on well-established, efficient and stable modern numerical linear techniques for mathematical problems arising in the design and analysis of linear control systems both for the first- and second-order models. Unique coverage of modern mathematical concepts such as parallel computations, second-order systems, and large-scale solutions Background material in linear algebra, numerical linear algebra, and control theory included in text Step-by-step explanations of the algorithms and examples

Linear System Theory and Design - Chi-Tsong Chen 1984
Uses simple and efficient methods to develop results and design procedures, thus creating a non-exhaustive approach to presenting the material; Enables the reader to employ the results to carry out design. Thus, most results are discussed with an eye toward numerical computation; All design procedures in the text can be carried out using any software package that includes singular-value decomposition, and the solution of linear algebraic equations and the Lyapunov equation; All examples are developed for numerical computation and are illustrated using MATLAB, the most widely available software package.

Solutions Manual for "Linear System Theory and Design, Third Edition" - Chi-Tsong Chen 1998-08-01
This Solutions Manual is designed to accompany Linear System Theory and Design, Third Edition by C.T. Chen, and includes fully worked out solutions to problems in the main text. It is available free to adopters of the text.